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12-14 June 2007, at US Naval Academy, Annapolis, MD

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Report Documentation Page

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Efficient Modeling & Simulation of Biological Warfare Using Innovative Design of Experiments Methods

Presented at
75th MORS Symposium
12, 13 & 14 June 2007

Thomas A. Donnelly, Ph.D. (ECBC), Erin E. Shelly (ECBC), and Daniel P. Cinotti (SAIC)

<u>DISCLAIMER</u>: The findings presented in this briefing are not to be construed as an official Department of the Army position unless so designated by other authorizing documents.

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Quicker answers, lower costs, solve bigger problems

- Obtain a fast and cheap surrogate "meta-model" of the simulation
 - can more rapidly answer "what if?" questions
 - do sensitivity analysis
- By running efficient subsets of all possible combinations, one can - for the same resources and constraints – solve bigger problems
- O Be as cost effective as possible and run no more trials than are needed to get a useful answer



- Demonstrated how Design of Experiments (DOE)
 can be used to sequentially run groups of
 simulation trials to obtain better and better
 meta-models of the simulation model
- When control variables are all continuous and response variable is NON-stochastic, then "Smoothing" designs can be used to efficiently produce a meta-model of a simulation that is made up of a complex series of physical models

Two Types of Designs for Two Types of Meta-Modeling of Simulations

- "Traditional" designs for polynomial modeling with categorical and continuous variables
 - Designs can be sequentially constructed to support increasingly complex models
 - Featured example reanalyzes a simulation case matrix in which all 648 combinations of variable settings were originally run
- "Smoothing" designs for use with continuous variables AND non-stochastic responses
 - O Though little used, these designs are a more efficient alternative to traditional designs and exploit "Kriging" regression analysis

Traditional Designs for Polynomial Modeling

- If a "textbook" fractional-factorial, orthogonal array or response-surface design is available, then use it.
- Textbooks and web site catalogs do not always contain designs for categorical variables with:
 - all combinations of mixed numbers of levels (e.g. 3, 4, 5, and 21)
 - large numbers of levels for variables (e.g. 5+)
- Algebraic (Orthogonal Array) and algorithmic (D-optimal)
 computer generated designs can often be used
 - Orthogonal Arrays are good at yielding analysis with "clean" (unconfounded) estimates of the "main effects"
 - O D-optimal designs are good for adding on the fewest additional trials to support higher order "interaction" terms in the model

Case Matrix (TBM Bulk) & Example Dosage Plot as Used in Study of the Observed Response "Probability of Casualty" (PCAS)

Variable	# Levels	Levels				
Agent Codes ¹	6	A, N, T, H, R, Y (categorical)				
Season	3	Winter, Summer, Spring/Fall (categorical)				
Time of Attack	3	0500, 1200, 2200 Local Time (continuous)				
No. of TBMs & Spread Radius ²	2	1 TBM & 1 m, 2 TBMs & 1000 m (categorical)				
Mass ^{3,4} (relative)	3	1.00, 1.57, 2.00 (continuous)				
Height of Burst ⁵	2	0, 10 m (continuous)				
Total Cases	648					

- 1. Dropped "Q" it had smallest effect & 6 levels allowed for use of a smaller Orthogonal Array
- 2. Spread Radius paired with No. of TBMs
- 3. Mass (with 3 levels) replaced Source Strength (with 2 levels)
- 4. Mass is nested in Agent
- 5. Data was available for Height of 10 m



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- Because a different set of mass values were used for each agent, the variable Mass is "nested" within the variable Agent
- The response Probability of Casualty (PCAS), which is bounded within the range (0, 1), was transformed using 2*Arcsin((PCAS)^{1/2}) which maps the range (0, 1) to the range (-∞, +∞)
 - This made the error fit the usual regression assumption of being normally distributed
 - This also prevented our regression from predicting values and limits that were above 1.0 and physically impossible



Stage 1

Stage 2

Stage 3

Stage 4

36 Total Simulations

108 Total Simulations

324 Total Simulations

ALL **648** Simulations

Design 1, 36 trials

Design 1, 36 trials

Design 1, 36 trials

Design 1, 36 trials

Design 2, 72 trials

Design 2, 72 trials

Design 2, 72 trials

Main effects only for ALL variables

Stage 1 effects plus all 2-way interactions

Design 3, 216 trials

Stage 2 effects plus all 3-way interactions

Design 3, 216 trials

Stage 3 effects plus ALL remaining 4-way, 5-way and 6-way interactions

5.6% of 648

16.7% of 648

50% of 648

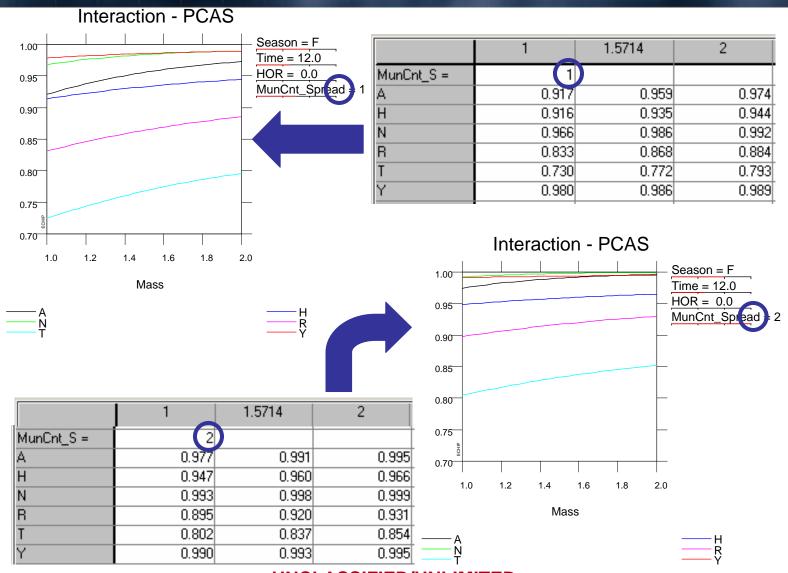
Design 4, 324 trials

NOTE: Length of this green box should be longer than shown

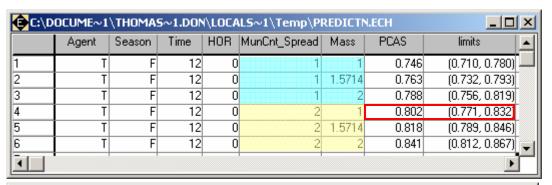
324 trials in Design 4 used as checkpoints for Designs 1, 2 & 3

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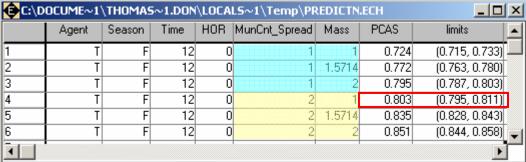
Tabled (Categorical) vs. Plot (Continuous) Predictions of PCAS for 2nd Order Model



Predictions (w/95% Pred. Limits) of PCAS vs. Nested Mass and MunCnt_Spread for 1-way, reduced 2-way and reduced 3-way models



1-way Model, Highlighted Prediction is 0.802 ± **0.030 Based on fitting 36** trials



2-way Model, Highlighted Prediction is 0.803 ± **0.008 Based on fitting 108** trials

C:\D	C:\DOCUME~1\THOMAS~1.DON\LOCAL5~1\Temp\PREDICTN.ECH									
	Agent	Season	Time	HOR	MunCnt_Spread	Mass	PCAS	limits		
1	T	F	12	0	4	1	0.730	(0.730, 0.730)		
2	T	F	12	0	1	1.5714	0.772	(0.772, 0.772)		
3	T	F	12	0	1	2	0.793	(0.793, 0.793)		
4	T	F	12	0	2	forms	0.802	(0.802, 0.802)		
5	T	F	12	0	2	1.5714	0.837	(0.837, 0.837)		
6	T	F	12	0	2	2	0.854	(0.854, 0.854)		
1										

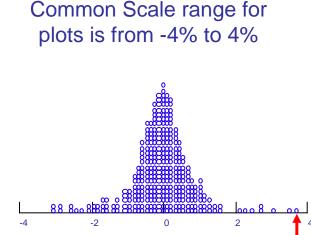
3-way Model, Highlighted Prediction is 0.802 ± **0.000 Based on fitting 324** trials

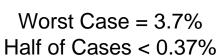
Percent Off Target for 324 PCAS Checkpoint Predictions with 1-Way, 2-Way and 3-Way Models "How Good is Good Enough?"



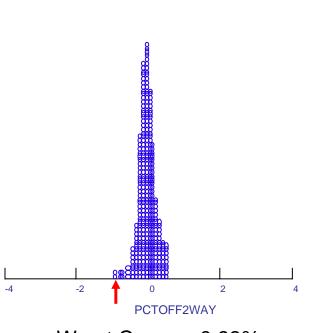


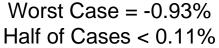
Reduced 3-way Model Fit to 36 + 72 + 216 Trials in Stage 3 Design

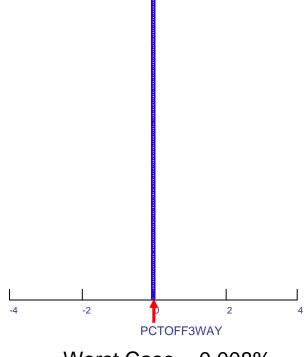




PCTOFF1WAY







Worst Case = 0.008% Half of Cases < 0.001%



Seminal Paper on "Smoothing*" DOE for Computer Experiments

- Sacks, J., Welch, W.J., Mitchell, T.J. and Wynn, H.P. (1989). "<u>Design and Analysis of Computer</u> <u>Experiments.</u>" *Statistical Science* 4. 409-423
 - O First textbook appeared in 2003 and has the same name
 - A good source for up-to-date information is the Simulation Experiments & Efficient Designs (SEED) Center for Data Farming at http://harvest.nps.edu
 - *Smoothing is an alternate name sometimes used for designs for computer experiments because it is a good description of the end result of the analysis. Another name that sometimes appears is "space-filling" designs because trials are spread somewhat uniformly throughout the test volume.



How are Smoothing Designs Different?

- From the traditional experimental design point of view the Smoothing designs – for the same number of trials – do not enclose as large a volume of the design space. This is intentional.
- Rather than emphasizing high leverage trials ("corners") for a simple polynomial model, these designs "spread" their trials more uniformly through the space to better capture the local complexities of the simulation model.
- Analysis employs "Kriging" method originally developed for geo-spatial regression



Optimization of Modeled Industrial Process Using Computer Experiments

- Data is generated by a simulation consisting of a series of physical/chemical models each feeding its result into the next.
- Industrial examples include:
 - **Ochemical plant**
 - **OAircraft engines**
 - ODeep ocean oil production
 - **OSemiconductor fabrication line**
 - OAluminum can extruder

Ran 51 "designed" simulation trials, analyzed data, determined optimal factor settings, checked optimum with a simulation trial (they agreed), built 1 real machine for \$500,000 and made real cans – the performance was "dead on"

 DoD examples include M&S like the ECBC Chem-Bio Sim Suite, SOES Smoke Model, etc.



Thomas J. Santner Brian J. Williams William I. Notz The Design and Analysis of Computer Experiments

C.3 Examples

The following examples demonstrate many possible uses of PErK. The responses for these examples are based on the *Branin function*. The Branin function is the real-valued function of two variables

$$y_{\mathcal{B}}(x_1, x_2) = \left(x_2 - \frac{5.1}{4\pi^2}x_1^2 + \frac{5}{\pi}x_1 - 6\right)^2 + 10\left(1 - \frac{1}{8\pi}\right)\cos(x_1) + 10$$

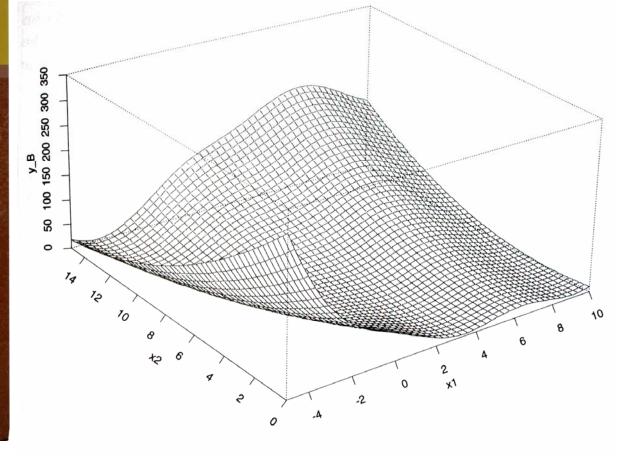
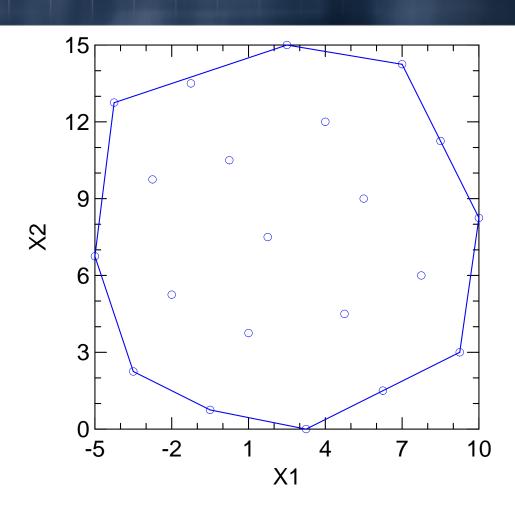


FIGURE C.1. The Branin function on $[-5, 10] \times [0, 15]$

Example Latin Hypercube Design and Data Calculated with Branin Function

Trial	X1	X2	Y
1	7.75	6	35.80951
2	1	3.75	14.86287
3	10	8.25	31.41880
4	4.75	4.5	19.87899
5	2.5	15	141.88566
6	-3.5	2.25	99.43335
7	3.25	0	3.88973
8	-5	6.75	97.47380
9	-4.25	12.75	6.27060
10	6.25	1.5	19.85914
11	8.5	11.25	95.50587
12	7	14.25	181.74214
13	-0.5	0.75	49.39445
14	-2	5.25	23.13762
15	0.25	10.5	43.09524
16	9.25	3	2.82392
17	-2.75	9.75	3.61474
18	5.5	9	75.79100
19	4	12	104.11175
20	-1.25	13.5	43.33586
21	1.75	7.5	23.39797



C.3 Examples

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$$y_{\mathcal{B}}(x_1, x_2) = \left(x_2 - \frac{5.1}{4\pi^2}x_1^2 + \frac{5}{\pi}x_1 - 6\right)^2 + 10\left(1 - \frac{1}{8\pi}\right)\cos(x_1) + 10$$

Trial	X1	X2	Y
1	7.75	6	35.80951
2	1	3.75	14.86287
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8	-5	6.75	97.47380
9	-4.25	12.75	6.27060
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20	-1.25	13.5	43.33586
21	1.75	7.5	23.39797

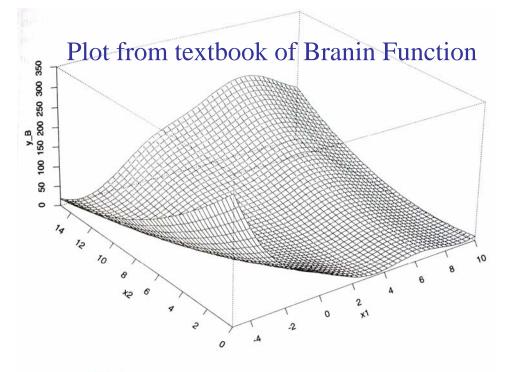
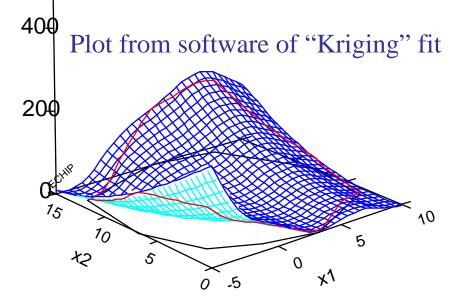
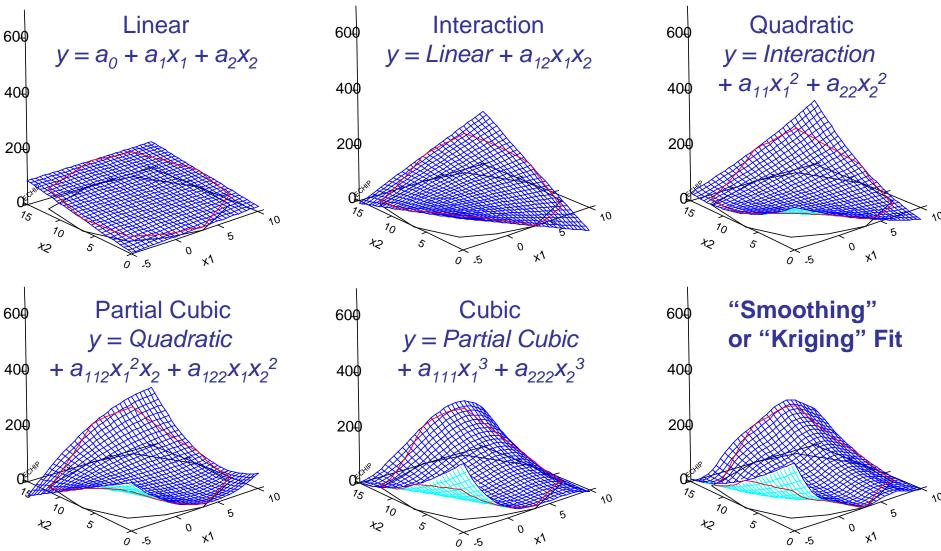


FIGURE C.1. The Branin function on $[-5, 10] \times [0, 15]$



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Comparing Surfaces for Increasingly Complex Polynomials Fit to Data from the Branin Function



The full *cubic* model appears to closely approximate the Branin function, but still cannot represent the ripples seen in the fit using Kriging method.



- Branin function example is trivial. With 2 control variables the full cubic model has 10 terms.
- The following example has 10 control variables.
 (Full cubic model has 166 terms!)
- Three different Smoothing designs are used:
- 1. 17-trial Latin Hypercube (LHC) design
- 2. 33-trial Nearly Orthogonal Latin Hypercube (NOLH) design (see SEED web site at http://harvest.nps.edu)
- 3. 50-trial Orthogonal Array (OA) design.
- Smoothing design trials combine in such a way as to fall into 5 of 6 Pasquill Atmospheric Stability regions within the VLSTRACK model

Pasquill Atmospheric Stability Classes & Meteorological Conditions That Define Them

Stability Class	Definition
A	very unstable
В	unstable
С	slightly unstable
D	neutral
E	slightly stable
F	stable

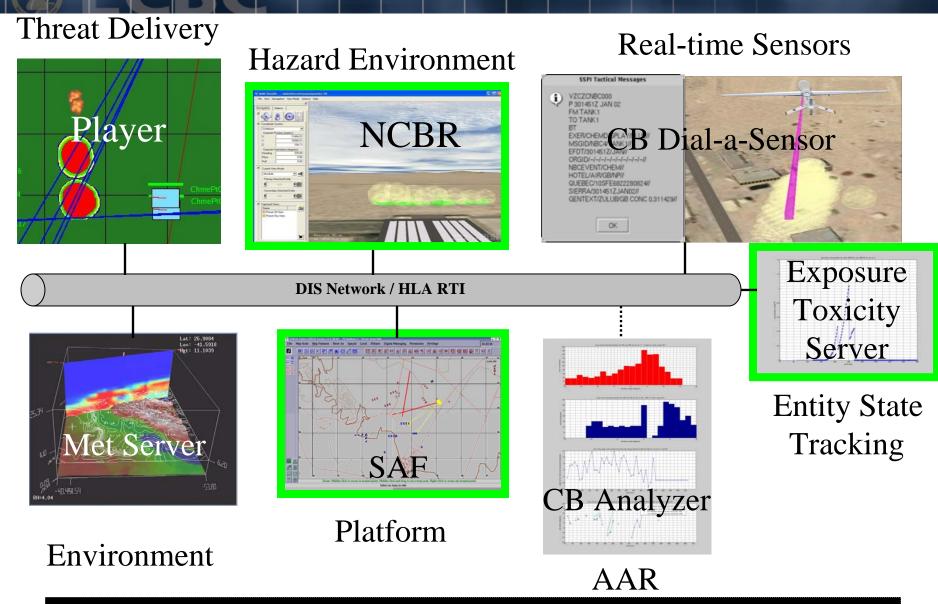
Key point is that VLSTRACK models each class a bit differently and we want to create a single meta-model of all classes together

Surface Wi	nd Speed	Daytime I	ncoming Solar	Nighttime Cloud Cover		
m/s	mi/hr	Strong Moderate Slight		> 50%	< 50%	
< 2	< 5	Α	A - B	В	E	F
2 to 3	5 to 7	A - B	В	C	E	F
3 to 5	7 to 11	В	B - C	C	D	E
5 to 6	11 to 13	С	C - D	D	D	D
> 6	> 13	С	D	D	D	D

TABLES SOURCE: http://en.wikipedia.org/wiki/Air_pollution_dispersion_terminology#_note-7#_note-7

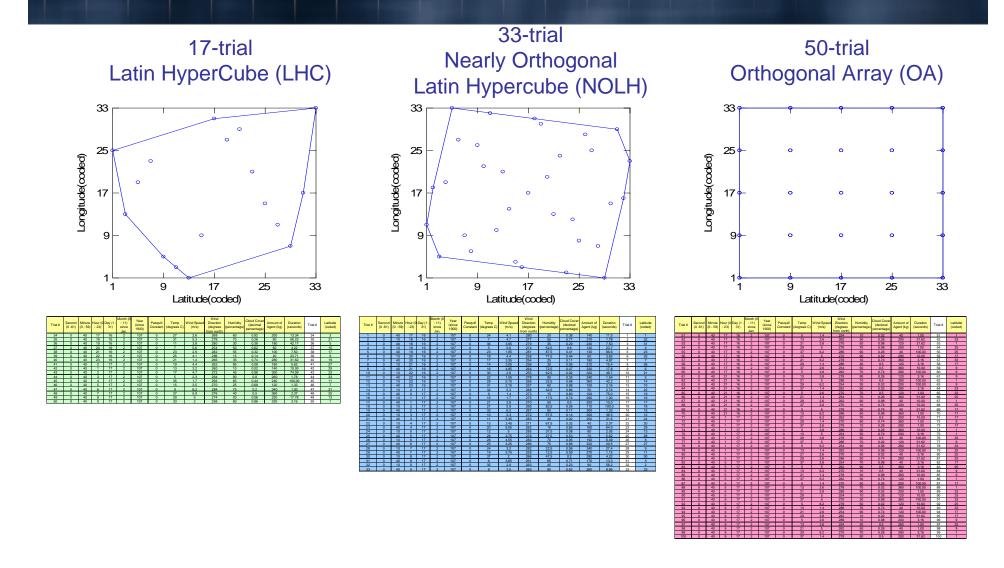
ORIGINAL SOURCE: Pasquill, F. (1961). *The estimation of the dispersion of windborne material*, The Meteorological Magazine, vol 90, No. 1063, pp 33-49.

CB Simulation Suite Architecture



CB Sim Suite is a set of distributed simulation tools designed to represent all aspects of CB passive defense on the tactical battle field for application to analysis, testing, and training.

Projections in 2-D for 3 Different 10-Variable "Smoothing" Designs of Size 17, 33 & 50 Trials



50-trial Orthogonal Array with 5 Levels per Variable

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TRIAL	time_wrt_sunset	Temp	Wind_speed	Wind_direction	Humidity	Cloud_Cover	Amount_Agent	Log(duration)	Latitude(coded)	Longitude(coded)
51	-120	5	1.4	254	10	0.02	40	0	1	1
52	-120	13	2.6	262	30	0.26	200	1.5	33	1
53	-120	21	3.8	270	50	0.98	120	1.5	1	17
54	-120	29	5	278	70	0.98	200	0	25	į (
55		37	6.2	286	90		40	2	25	
56	-120	13	5	270	90	0.02	280	1	17	25
57	-120	21	6.2	278	10	0.74	360	0.5	33	25
58	-120	29	1.4	286	30	0.5	120	0.5	17	30
59	-120	37	2.6	254	50	0.5	360	1	9	(
60	-120	5	3.8	262	70	0.74	280	2	9	30
61	120	13	3.8	278	90	0.26	120	0.5	9	(
62	120	21	5	286	10	0.5	280	2	1	(
63	120	29	6.2		30		200		9	25
64	120	37	1.4	262	50	0.02	280	0.5	33	
65	120	5	2.6	270	70		120	0	33	25
66		21	1.4		70		360	1.5	25	
67	120	29	2.6	262	90	0.98	40	1	1	33

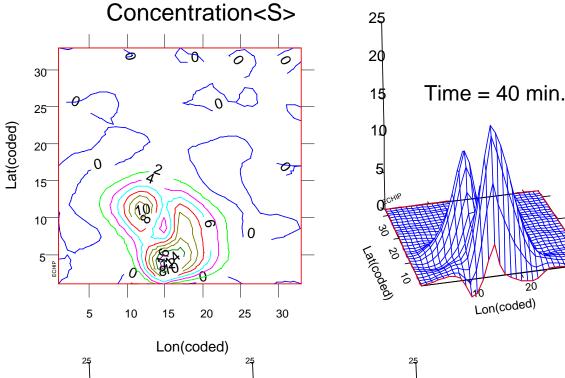
Showing first 17 of 50 trials in one "space-filling" design out of $5^{10} = 9,765,625$ possible combinations of variable settings

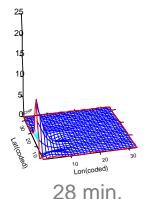
Kriging Analysis of a Single Simulation – Concentration vs. Latitude, Longitude & Time

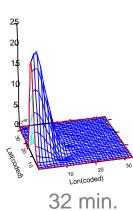
Cloud release point is 10 km west of 10 km X 10 km grid of 72 identical entities

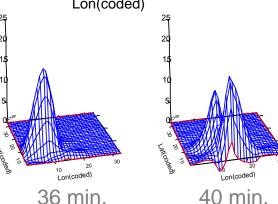


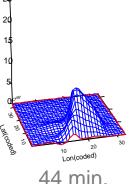
Wind speed is 5.3 m/s Wind direction is 278° from north

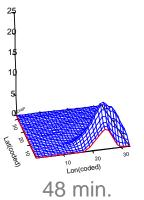






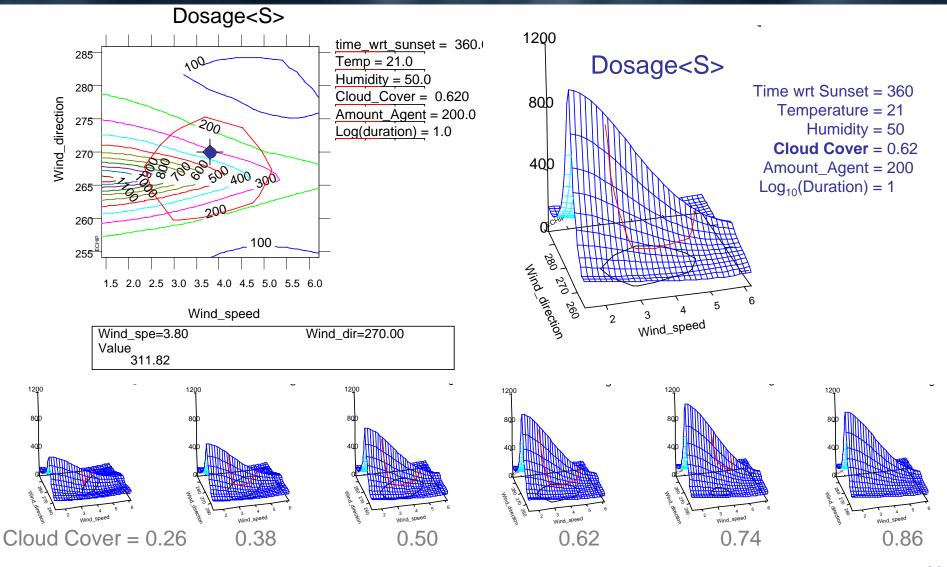






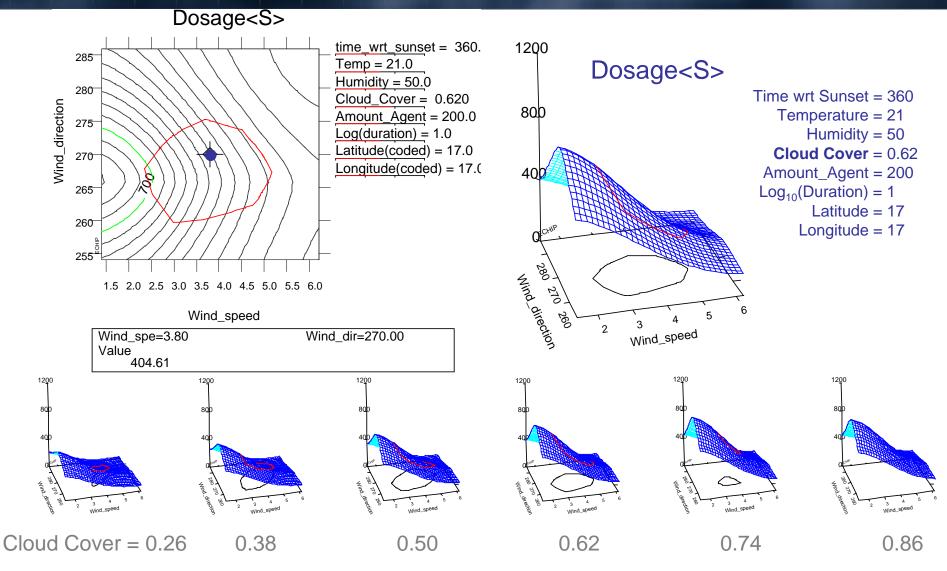
30

Kriging Analysis of 17 LHC Simulations Using 17 Observations Max Dosage vs. 8 Variables

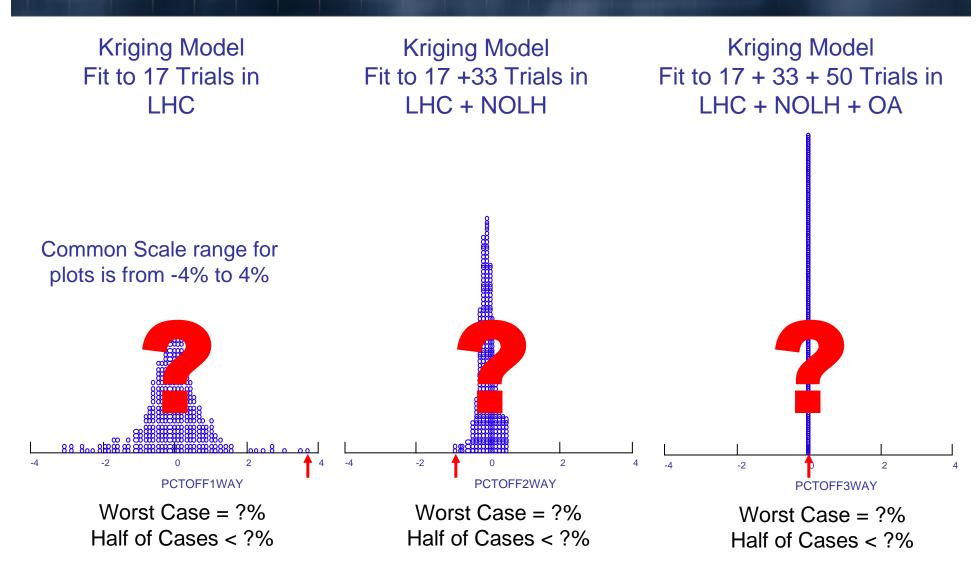


Kriging Analysis of 17 L

Kriging Analysis of 17 LHC Simulations Using 1209 Observations = 17 X 72 – 15 Max Dosage vs. 10 Variables

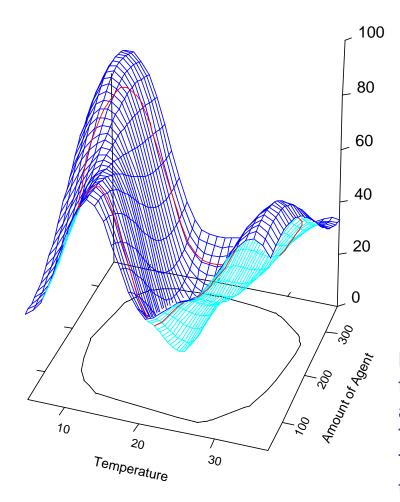


In Future Will Show % Off Target for 200 Checkpoint Predictions with Various Smoothing Designs "Suspect - Never Get Something for Nothing"



Kriging Analysis of Random Data!

10-Variable Meta-Model Predicting Concentration



Off-Axis Variable Settings

Time wrt Sunset = 360
Wind Speed = 3.8
Wind Direction = 270
Humidity = 50
Cloud Cover = 0.50
Log₁₀(Duration) = 1.0
Latitude (coded) = 17
Longitude (coded) = 17

NOTE: This is a plot of Kriging regression of the 100 integers between 0 and 99 randomly assigned to 100 smoothing design trials. The "noise" has been fit perfectly! This is why one should only use this technique with non-random data!



- Demonstrated how Design of Experiments (DOE) can be used to sequentially run groups of simulation trials to obtain better and better meta-models of the simulation model
- When control variables are all continuous and response variable is NON-stochastic, then "Smoothing" designs can be used to efficiently produce a meta-model of a simulation that is made up of a complex series of physical models